Mathematics 160: Lecture 4

Homogeneous Systems

Dan Sloughter

Furman University

August 31, 2011

oan Sloughter (Furman University)

Mathematics 160: Lecture 4

August 31, 2011

. 1/10

Dan Sloughter (Furman University

Mathematics 160: Lecture 4

August 31, 2011 2

Example

• In a previous example, we saw that the row echelon form of

$$A = \begin{bmatrix} 1 & -1 & -1 & 2 & 1 \\ 2 & -2 & -1 & 3 & 3 \\ -1 & 1 & -1 & 0 & -3 \end{bmatrix}.$$

is

$$\begin{bmatrix} 1 & -1 & -1 & 2 & 1 \\ 0 & 0 & 1 & -1 & 1 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}.$$

• Hence rank(A) = 2.

Rank

- We will eventually prove that the reduced row-echelon form of a matrix is unique.
- The row echelon form of a matrix is not unique, but the number of leading 1's in a row echelon form is unique.
- Definition: We call the number of leading 1's in a row echelon form of a matrix A the rank of A, which we denote rank(A).
- Note: Consider a consistent system of m linear equations in n variables. If r is the rank of the augmented matrix, then the system has r leading variables and n-r nonleading variables. Hence the set of solutions has n-r parameters.

Solution sets

- Theorem: Given a system of linear equations, there are either
 - no solutions,
 - exactly one solution,
 - an infinite number of solutions.

Definitions

• We say a system of linear equations of the form

$$a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n = 0$$

$$a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n = 0$$

$$\vdots$$

$$a_{m1}x_1 + a_{m2}x_2 + \dots + a_{mn}x_n = 0$$

is homogeneous.

• Note: a homogeneous system always has the trivial solution

$$X = \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix}.$$

Nontrivial solutions

- Theorem: Consider a homogeneous system of m linear equations and *n* variables. Let *r* be the rank of the coefficient matrix. If r < n, then the system has nontrivial solutions.
- Note: in particular, if m < n, then the system has nontrivial solutions.

Solution sets

- Suppose the rank of the augmented matrix for a homogeneous system of linear equations in n variables is r.
- Assign parameters $s_1, s_2, \ldots, s_{n-r}$ to the n-r nonleading variables.
- Then every solution to the system is of the form

$$X = s_1 X_1 + s_2 X_2 + \cdots + s_{n-r} X_{n-r}$$

where $X_1, X_2, \ldots, X_{n-r}$ are $n \times 1$ column matrices.

- Note: each of $X_1, X_2, \ldots, X_{n-r}$ is itself a solution of the system. We call these the basic solutions.
- In short: every solution to a homogeneous system of linear equations is a linear combination of basic solutions.

Example

• The homogeneous system

$$x_1 + 2x_2 - 2x_3 - 12x_4 = 0$$

$$x_1 + 3x_2 - 18x_4 + 6x_5 = 0$$

$$x_1 - 6x_3 - 12x_5 = 0$$

has augmented matrix

$$\begin{bmatrix} 1 & 2 & -2 & -12 & 0 & 0 \\ 1 & 3 & 0 & -18 & 6 & 0 \\ 1 & 0 & -6 & 0 & -12 & 0 \end{bmatrix}.$$

Example (cont'd)

Applying row operations, the augmented matrix becomes

$$\begin{bmatrix} 1 & 2 & -2 & -12 & 0 & 0 \\ 0 & 1 & 2 & -6 & 6 & 0 \\ 0 & -2 & -4 & 12 & -12 & 0 \end{bmatrix}$$

$$\longrightarrow \begin{bmatrix} 1 & 2 & -2 & -12 & 0 & 0 \\ 0 & 1 & 2 & -6 & 6 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}.$$

• If we let $x_3 = s$, $x_4 = t$, and $x_5 = u$, then $x_2 = -2s + 6t - 6u$ and $x_1 = -2(-2s + 6t - 6u) + 2s + 12t = 6s + 12u.$

Example (cont'd)

Hence the solutions are

$$X = s \begin{bmatrix} 6 \\ -2 \\ 1 \\ 0 \\ 0 \end{bmatrix} + t \begin{bmatrix} 0 \\ 6 \\ 0 \\ 1 \\ 0 \end{bmatrix} + u \begin{bmatrix} 12 \\ -6 \\ 0 \\ 0 \\ 1 \end{bmatrix}.$$

The basic solutions are

$$X_1 = \begin{bmatrix} 6 \\ -2 \\ 1 \\ 0 \\ 0 \end{bmatrix}, X_2 = \begin{bmatrix} 0 \\ 6 \\ 0 \\ 1 \\ 0 \end{bmatrix}, X_3 = \begin{bmatrix} 12 \\ -6 \\ 0 \\ 0 \\ 1 \end{bmatrix}.$$

Example

• Recall: given real numbers a, b, c, d, e, and f, with not all of a, b, and c zero, the graph of the equation

$$ax^2 + bxy + cy^2 + dx + ey + f = 0$$

is a conic section.

• To find a conic section passing through the five points (p_1, q_1) , $(p_2, q_2), (p_3, q_3), (p_4, q_4), \text{ and } (p_5, q_5), \text{ we would need to solve}$

$$p_1^2 a + p_1 q_1 b + q_1^2 c + p_1 d + q_1 e + f = 0$$

$$p_2^2 a + p_2 q_2 b + q_2^2 c + p_2 d + q_2 e + f = 0$$

$$p_3^2 a + p_3 q_3 b + q_3^2 c + p_3 d + q_3 e + f = 0$$

$$p_4^2 a + p_4 q_4 b + q_4^2 c + p_4 d + q_4 e + f = 0$$

$$p_5^2 a + p_5 q_5 b + q_5^2 c + p_5 d + q_5 e + f = 0.$$

Example (cont'd)

- Since this is a linear system of 5 equations in 6 variables, by the previous theorem, there exist nontrivial solutions. If the five points do not lie on a line, then we cannot have a, b, and c all zero.
- Conclusion: given five points in the plane, not all on a line, there exists a conic passing through them.

Dan Sloughter (Furman University)

August 31, 2011

Dan Sloughter (Furman University)

August 31, 2011

Example

• To find a conic section passing through the points (2,1), (-2,1), (1,3), (1,-3), and (-1,3), we need to solve

$$4a + 2b + c + 2d + e + f = 0$$

$$4a - 2b + c - 2d + e + f = 0$$

$$a + 3b + 9c + d + 3e + f = 0$$

$$a - 3b + 9c + d - 3e + f = 0$$

$$a - 3b + 9c - d + 3e + f = 0$$

Example (cont'd)

• Using Octave, we row reduce the augmented matrix:

$$\begin{bmatrix} 4 & 2 & 1 & 2 & 1 & 1 & 0 \\ 4 & -1 & 1 & -2 & 1 & 1 & 0 \\ 1 & 3 & 9 & 1 & 3 & 1 & 0 \\ 1 & -3 & 9 & 1 & -3 & 1 & 0 \\ 1 & -3 & 9 & -1 & 3 & 1 & 0 \end{bmatrix}$$

0.00000T1.0000 0.00000 0.00000 0.00000 0.00000 0.22857 0.0000 1.00000 0.00000 0.00000 0.00000 0.00000 0.00000 0.0000 0.00000 1.00000 0.00000 0.00000 0.00000 0.08571 0.0000 0.00000 0.00000 1.00000 0.00000 0.00000 0.00000 0.0000 0.00000 0.00000 0.00000 1.00000 0.00000 0.00000

Example (cont'd)

• Hence, for any real number s we have solutions

$$X = s \begin{bmatrix} -0.22857 \\ 0 \\ -0.08571 \\ 0 \\ 0 \\ 1 \end{bmatrix}$$

• For example, with s = -1, we have the equation

$$0.22857x^2 + 0.08571y^2 = 1,$$

an ellipse.

Example (cont'd)

• Graph of $0.22857x^2 + 0.08571y^2 = 1$:

