Mathematics 160: Lecture 8 Inverses and Elementary Matrices

Dan Sloughter

Furman University

September 12, 2011

Computing an inverse

- The proofs of the previous lecture provide a method for finding inverses.
- Namely: given an $n \times n$ matrix A, let C_1, C_2, \ldots, C_n be the solutions of $AX = E_j$, where, for j = 1, 2, ..., n, E_j is the $n \times 1$ column matrix $[e_{i1}]$ with

$$e_{i1} = \begin{cases} 1, & \text{if } i = j, \\ 0, & \text{if } i \neq j. \end{cases}$$

Then A^{-1} is the matrix with columns C_1, C_2, \ldots, C_n

- Note: this requires solving *n* systems of *n* equations in *n* unknowns.
- Note: we can do this at once by writing an augmented matrix consisting of A and I_n and reducing A to I_n .
- That is, the same row operations which take A to I_n take I_n to A^{-1} .

Example

We will find the inverse of

$$A = \begin{bmatrix} 1 & 2 & -1 \\ 2 & 2 & 4 \\ 1 & 3 & -3 \end{bmatrix}.$$

Using elementary row operations, we find

$$\begin{bmatrix} 1 & 2 & -1 & & 1 & 0 & 0 \\ 2 & 2 & 4 & & 0 & 1 & 0 \\ 1 & 3 & -3 & & 0 & 0 & 1 \end{bmatrix} \longrightarrow \begin{bmatrix} 1 & 2 & -1 & & 1 & 0 & 0 \\ 0 & -2 & 6 & & -2 & 1 & 0 \\ 0 & 1 & -2 & & -1 & 0 & 1 \end{bmatrix}$$

Example (cont'd)

Continuing, we have

$$\begin{bmatrix} 1 & 2 & -1 & 1 & 0 & 0 \\ 0 & -2 & 6 & -2 & 1 & 0 \\ 0 & 1 & -2 & -1 & 0 & 1 \end{bmatrix} \longrightarrow \begin{bmatrix} 1 & 2 & -1 & 1 & 0 & 0 \\ 0 & 1 & -3 & 1 & -\frac{1}{2} & 0 \\ 0 & 1 & -2 & -1 & 0 & 1 \end{bmatrix}$$
$$\longrightarrow \begin{bmatrix} 1 & 0 & 5 & -1 & 1 & 0 \\ 0 & 1 & -3 & 1 & -\frac{1}{2} & 0 \\ 0 & 0 & 1 & -2 & \frac{1}{2} & 1 \end{bmatrix} \longrightarrow \begin{bmatrix} 1 & 0 & 0 & 9 & -\frac{3}{2} & -5 \\ 0 & 1 & 0 & -5 & 1 & 3 \\ 0 & 0 & 1 & -2 & \frac{1}{2} & 1 \end{bmatrix}.$$

Hence

$$A^{-1} = \begin{bmatrix} 9 & -\frac{3}{2} & -5 \\ -5 & 1 & 3 \\ -2 & \frac{1}{2} & 1 \end{bmatrix}.$$

Dan Sloughter (Furman University)

September 12, 2011

Dan Sloughter (Furman University)

September 12, 2011

Example

Suppose we wish to find an inverse for

$$A = \begin{bmatrix} 2 & 1 & -4 \\ -4 & -1 & 6 \\ -2 & 2 & -2 \end{bmatrix}.$$

• Using elementary row operations, we find that

$$\begin{bmatrix} 2 & 1 & -4 & 1 & 0 & 0 \\ -4 & -1 & 6 & 0 & 1 & 0 \\ -2 & 2 & -2 & 0 & 0 & 1 \end{bmatrix} \longrightarrow \begin{bmatrix} 2 & 1 & -4 & 1 & 0 & 0 \\ 0 & 1 & -2 & 2 & 1 & 0 \\ 0 & 3 & -6 & 1 & 0 & 1 \end{bmatrix}$$

Example (cont'd)

Continuing, we have

$$\begin{bmatrix} 2 & 1 & -4 & & 1 & 0 & 0 \\ 0 & 1 & -2 & & 2 & 1 & 0 \\ 0 & 3 & -6 & & 1 & 0 & 1 \end{bmatrix} \longrightarrow \begin{bmatrix} 2 & 1 & -4 & & 1 & 0 & 0 \\ 0 & 1 & -2 & & 2 & 1 & 0 \\ 0 & 0 & 0 & & -5 & -3 & 1 \end{bmatrix}.$$

- Note: this shows that it is not possible to reduce A to I_3 using elementary row operations.
- It follows that A does not have an inverse.

Inverses in Octave

To find the inverse of

$$A = \begin{bmatrix} 1 & 2 & 3 \\ -1 & 0 & 1 \\ 4 & 2 & 1 \end{bmatrix},$$

we can either

apply rref to the augmented matrix

$$\begin{bmatrix} 1 & 2 & 3 & 1 & 0 & 0 \\ -1 & 0 & 1 & 0 & 1 & 0 \\ 4 & 2 & 1 & 0 & 0 & 1 \end{bmatrix},$$

- or use inv(A).
- In either case, we find that

$$A^{-1} = \begin{bmatrix} -1.0000 & 2.0000 & 1.0000 \\ 2.5000 & -5.5000 & -2.0000 \\ -1.0000 & 3.0000 & 1.0000 \end{bmatrix}$$

Definition

- An elementary matrix is any matrix which may be obtained by applying an elementary row operation to an identity matrix.
- Examples: Each of the following is an elementary matrix:

$$\begin{bmatrix} 2 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}, \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix}, \text{ and } \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ -5 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}.$$

Example

Let

$$A = \begin{bmatrix} 1 & 2 & 3 & 1 \\ 4 & 5 & 6 & 2 \\ 7 & 8 & 9 & 1 \end{bmatrix} \text{ and } E = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 1 \end{bmatrix}.$$

- Note: E is an elementary matrix obtained by multiplying the second row of I_3 by 3.
- Note:

$$EA = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 2 & 3 & 1 \\ 4 & 5 & 6 & 2 \\ 7 & 8 & 9 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 2 & 3 & 1 \\ 12 & 15 & 18 & 6 \\ 7 & 8 & 9 & 1 \end{bmatrix},$$

which is what we would obtain applying the same elementary row operation to A.

Example (cont'd)

Let

$$E = \begin{bmatrix} 1 & 0 & 0 \\ 3 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix},$$

the elementary 3×3 matrix obtained by adding 3 times the first row to the second row of I_3 .

Now

$$EA = \begin{bmatrix} 1 & 0 & 0 \\ 3 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 2 & 3 & 1 \\ 4 & 5 & 6 & 2 \\ 7 & 8 & 9 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 2 & 3 & 1 \\ 7 & 11 & 15 & 5 \\ 7 & 8 & 9 & 1 \end{bmatrix},$$

which is what we would obtain from applying the same row operation to A.

Example (cont'd)

Let

$$E = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix},$$

the elementary 3×3 matrix obtained by interchanging the second and third rows of I_3 .

Then

$$EA = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} 1 & 2 & 3 & 1 \\ 4 & 5 & 6 & 2 \\ 7 & 8 & 9 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 2 & 3 & 1 \\ 7 & 8 & 9 & 1 \\ 4 & 5 & 6 & 2 \end{bmatrix},$$

which is what we would obtain from applying the same row operation to A.

Row operations

- Suppose an elementary row operation is performed on an $m \times n$ matrix A to obtain the matrix B.
- Let E be the elementary matrix obtained by performing the same row operation on I_m .
- Then B = EA.

Inverses of elementary matrices

- Every elementary matrix E is invertible, and E^{-1} is itself an elementary matrix:
 - If E multiplies a row by a nonzero scalar c, E^{-1} multiplies that same
 - If E multiplies row i by scalar c and adds it to row i, E^{-1} multiplies row i by -c and adds it to row j.
 - If E interchanges rows i and j, E^{-1} interchanges rows i and j (and. so. $E = E^{-1}$).

Dan Sloughter (Furman University)

Theorem

• If A is an invertible matrix, then there exist elementary matrices E_1 , $E_2, \ldots E_k$ such that

$$A = E_1 E_2 \cdots E_k$$
.

- Reason:
 - Since A is reducible to I, there exist elementary matrices D_1, D_2, \ldots D_k such that

$$I = D_k D_{k-1} \cdots A$$
.

Hence

$$A = D_1^{-1} D_2^{-1} \cdots D_k^{-1}.$$

• So let $E_i = D_i^{-1}$, i = 1, 2, ..., k.

Theorem

series of elementary row operations. Then: • $B = E_k E_{k-1} \cdots E_1 A$, where E_1, E_2, \ldots, E_k are elementary matrices.

• Suppose an $m \times n$ matrix A is reducible to an $m \times n$ matrix B by a

- B = UA for some invertible matrix U.
- U is the matrix obtained from I_m by performing the row operations on I_m which reduce A to B.

Theorem

- If R and S are both reduced row-echelon forms of a matrix A, then R=S.
- We will not prove this, but the proof is based on the following observations:
 - There exist invertible matrices P and Q such that R = PA and S = QA.
 - Hence $A = Q^{-1}S$ and $A = P^{-1}R$, so $S = QP^{-1}R$.
 - That is, S = UR for some invertible matrix U.